



LIMO ROS2 robot features an Intel NCU i7 processor running ROS 2 on Ubuntu 22.04, providing an essential platform for autonomous mobile robot research and education.

LIMO ROS2 enables exploring ROS 2's latest capabilities, including prominent open-source frameworks like Navigation2 and MoveIt2. With an extended 2.5 hour battery life, it ensures uninterrupted operation.

As an ideal companion for students, researchers, and enthusiasts, LIMO PRO facilitates hands-on learning with cutting-edge robotic technology. Its professional-grade engineering and comprehensive feature set equip users to push boundaries in autonomous systems.

Highlight

- **Robust Hardware:** Powered by an Intel NCU i7 for high performance in autonomous vehicle applications.
- **Simulation and Navigation:** LIMO ROS2 excels in mobile robot navigation simulation.
- **Smart Motion Planning:** It features advanced robotic arm motion planning using MoveIt2.

- Long-lasting Power: Enjoy up to 2.5 hours of uninterrupted research and experimentation.

Tech specifications

Items	Parameters	Values	
Mechanical	Overall dimension	322*220*251mm	
	Wheel base	200mm	
	Tread	175mm	
	Dead load	4.8kg	
	Load		1kg (Four-wheel differential)
			4kg (Ackermann mode)
			4kg (Wheat wheel)
	Minimum ground clearance	24mm	
Drive type	Hub motor (4x14.4W)		
Performance	No-load max. speed	1m/s	
	Ackermann minimum turning radius	0.4m	
	Work environment	-10~+40°C	
	Max. climbing capacity	40° (under track mode)	
System	Power interface	DC (5.5x2.1mm)	
	OS	Ubuntu22.04	
	IMU	HI226	
	CPU	i7-1135G7@2.40GHz x 8	
	GPU	Xe Graphics	
	Battery	10Ah 12V	
	Working time	2.5H	
	Stand-by time	4H	
	Communication interface	WIFI,Bluetooth	
Sensor	LIDAR	EAI T-mini Pro	
	Depth camera	DaBai	

	IPC	Intel NUC (8G)
	USB-HUB	TYPE-C x1, USB2.0 x2
	Front display	1.54 inch 128x64 white OLED display screen
	Rear display	7 inch touch screen
Control	Control mode	Mobile APP, command control
	Mobile APP	Bluetooth, maximum distance 10m